

Protention and retention in biological systems

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Abstract This paper proposes an abstract mathematical frame for describing some features of cognitive and biological time. We focus here on the so called “extended present” as a result of protentional and retentional activities (memory and anticipation). Memory, as retention, is treated in some physical theories (relaxation phenomena, which will inspire our approach), while protention (or anticipation) seems outside the scope of physics. We then suggest a simple functional representation of biological protention. This allows us to introduce the abstract notion of “biological inertia”.

Keywords Memory and Cognition · protention · retention · biological time.

Introduction

The notions of “memory” and “anticipation” are analyzed here from a temporal perspective. By this, we propose a simple mathematical approach to *retention* and *protention* that are apparently shared by all organisms, albeit rudimentarily. Moreover, in life phenomena, memory is essential to learning and it is oriented towards action, the grounding of protention. Our approach will allow to address the issue of what we call “biological inertia”, a form of “continuation” of ongoing action, derived from the notions above. The frame is purely mathematical and abstract: only practitioners will be able to give values to our coefficients and develop, possibly, concrete applications of the approach, from cell biology to human cognition. Our aim is to give a precise and relevant meaning to notions that are usually

This paper was made possible only as part of an extended collaboration with Francis Bailly (see references), a dear friend and “maître à penser”, who contributed to the key ideas. Francis passed away in february 2008: we continue here our inspiring discussions and joint work.

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treated in a rather informal fashion and unrelated between one another, such as those of time of representation, time of retention and time of protention.

A long phenomenological tradition introduces an important distinction between memory and retention, on the one hand, and anticipation and protention on the other. In short, the common meaning of “memory” seems to essentially refer to a “conscious reconstruction” of something that was experienced (very well put by Edelman as a “brain which sets itself back into a previously experienced state”). Anticipation would be its temporal opposite — the awareness of an expectation, of a possible future situation. Memory and anticipation do not, a priori, have a biological *characteristic time*, a notion which is essential to our analysis. In our approach, instead, possibly pre-conscious retention is to be seen as an extension of the present; it is the present which is “retained”, during a brief interval of time (related to what will be called its characteristic time) for the objective of the action (and of perception), it is a form of extension of the immediate past into the present. For example, when listening to a word or a phrase, we retain the part which has already occurred for a certain (characteristic) duration of time. The mental duration of a phrase, particularly of a musical “phrase”, is needed for grasping meaning or a melody: it is the present which leaves a trace the time necessary for action or, possibly, for subsequent awareness. But protention (as preconscious anticipation) is essential to appreciate a melody or understand a phrase. When reading, the analysis of saccadic eye movements demonstrates that we first look at least at half of the word following the one we are reading. This protentional behaviour participates in the reconstruction of meaning: we appear to make sure of the meaning of the word we are reading by making a partial guess upon the following word.

Technically, protention will be given by a temporal mirror image, as it extends retention forwards into time. Protention is, above all, the *tropism* inherent to action performed by any life form. This point is at the center of our approach: we call retention and protention these particular aspects of memory and of anticipation that are specific to all life forms – a sort of present which is extended in both directions. Thus we do not limit our analysis to the phenomenological use of these words, inasmuch it limits their meaning to situations that can be examined through conscious activities. We believe that this extension to pre-conscious activities remains compatible with (and helps to understand) its classical usage, particularly such as described by Van Gelder (1999) and Varela (1999) who develop the concepts of intentionality, retention and of protention, introduced and discussed in length by Husserl in his analysis of human consciousness.

In this paper, it is then a question of trying to propose an elementary modelization of these inevitably fuzzy notions, one which is as rudimentary as possible, but one that can nevertheless support discussions regarding their precise conceptualization and their increasingly thorough mathematization. The introduction of the notions of “biological inertia” and “global protention” are, typically, a consequence of the generative power of mathematics.

To our aim, we will define some basic principles and more specific notions, after some methodological preliminaries.

Methodological remarks

This paper belongs to series of texts Bailly and Longo (2006, 2008, 2009); Bailly et al (2010) whose attempted aim is not to reconstruct the physico-mathematical complexity of some aspects of biology, but to propose firstly and above all a proper biological perspective. We believe that the *theoretical differentiation* between theories of inert and of living

phenomena requires, among other things, a change in the relevant *parameters* and *observables*. As long as the actions of living organisms, including their cognitive performances which occur the moment that life appears (in this sense, we speak of protention and of retention in the amoeba or the paramecium), are analyzed within physical space-time, the physico-mathematical takes precedent over the specificity of the biological. For example, the formidable mathematics of morphogenesis, from phyllotaxy to the analysis of the fractal structures of organs, organize the results of friction in the growth of living organisms according to physical geodesics. This friction is nevertheless shaped within physical space-time (fractality optimizes the occupation of physical space, the exchange of energy by a surface within a volume. . .). In all of these cases, the spatio-temporal and energetic parameters and observables enable a very interesting and often technically very difficult analysis. This is an approach of the *physical complexity* of living phenomena and of its material structures. We could also say the same of analyses of networks of cells, of which the most complex are neural networks. Informational interaction, often a gradient of energy, enables to develop a theory, now very rich from the mathematical standpoint, of these formal networks of which increasingly important applications are being considered for the construction of machines that are somewhat intelligent (at last).

In this paper, our mathematics will not go beyond a few equations which could be presented to high school students. What matters in our view is approaching biological time according to its own specificity, by starting with some invariants which appear to be *exclusively* specific to living phenomena, as we did in Bailly and Longo (2006), or with properties that are not treated by current physical theories, as protention here. In Bailly et al (2010), we proposed a two dimensional representation of biological time as a mathematical frame to accomodate the autonomous (internal) biological rhythms (cardiac, respiratory, metabolic rhythms . . .). In the perspective of this paper, one may understand the expectation or anticipation of a rhythm to iterate, as a minimal form of protention: once rhythms are installed, the organism is “tuned” to (and “expects”) their iteration.

Before developing a further geometrization of biological-time, we will face yet another taboo of physicalism in biology: the inverted causality specific to protention. We will not present a physical theory of teleonomy, but will use as data the evidence of protentional behaviours that may be observed in any life form. When the paramecium, encircled by a ring of salt, tries after many attempts to break through the obstacle, risking its own life and possibly even succeeding Misslin (2003), we can take note of the retention/memory-learning of what we see and of the ensuing teleonomic gesture (a protention) and develop an adequate theory (see Saigusa et al (2008)). Likewise, when we hear that the brain, prior to a saccadic eye movement, in an obvious anticipation, prepares the corresponding primary cortex which is apt to receive the new signal (see Berthoz (2002)), there is certainly an underlying physico-chemical mechanism which will one day enable to grasp the phenomenon by means of physical causality, a causality which may need to be invented. For the moment, let's consider these phenomena as a form of protention to be analyzed (correlated, formalized. . .) by a theory specific to living phenomena, even if it has no correspondence or meaning within current physical theories. Then, the unification with the physico-chemical theories may be better considered, in order to evidentiate the physico-chemical components which underlie these phenomena. As a matter of fact, unification will be possible only when we will have *two* theories to compare to one another, both theories being as mathematized as possible. We are talking about *unification* and not *reduction*, since physicists aim to unify the relativistic and quantum fields and not perform a reduction of the one *theory* to the other: string theory and non-commutative geometry aims the construction of a new unified frame which presents a new perspective for both theories. The mathematics to be found in the following pages will

give us the advantage of formalization: it forces to specify concepts and to stabilize them as much as possible (this is what mathematics is first about). Maybe that which follows is false, but it should then be possible to say so in relation to a precise formulation.

1 Characteristic time and correlation lengths

The notion of “characteristic time”, which we inherit here from physics, appears to be very important in biology as well: it concerns the unity of the living individual because, for example, fluxes and their transport entail lengths and, therefore, relevant transport times. We will also speak of characteristic times for retention and protention.

For example, according to the size of the organism, there appears to be two sorts of transport processes. For large organisms, it would be of a “propagational” type (v_p velocity, along networks and “channels”) with a typical correlation length of $L_p = v_p \tau$, where τ represents the characteristic time. For smaller organisms (cells, for example), it would rather be of a “diffusional” type (diffusion coefficient D , due to molecular diffusion processes) and the typical correlation length would be $L_d = (D\tau)^{\frac{1}{2}}$.

We stress the difference regarding dependency in function of time: linear in one case, as a power of $\frac{1}{2}$ in the other.

Two complementary remarks:

- The size of the organism also affects structures determining the mode of transport, for example the respiratory function (oxygen transport): in the case of small organisms (insects, for example) the transport is performed by *tracheas* (or even pores), multitudes of little cylinders where the air diffuses in order to reach the cells. In the case of large organisms (fish, mammals), transportation and exchanges are performed by means of *gills* or of *lungs*, centralized anatomic structures which present the fractal geometries we evoked above and which enable to conciliate difficultly compatible constraints (efficiency, steric limitation, homogeneity), and then by various sorts of vascular systems. Transportation, in this last case, is also much more of a “propagational” type (even if diffusion does play a role, namely in bronchioles).
- These considerations essentially apply to various *structural* aspects responding to identical functions. The *functional* aspect responds for its part very generally to common scaling laws (the metabolism which corresponds particularly to oxygen intake, the variegated rhythmicities, the relaxation times...). It therefore appears that the modes of transport associated to identical functions can be different and can correspond to different anatomic structures (tracheas, gills, bronchial trees/lungs). This is a conceptual configuration that we have already encountered and that we have related to what Edelman and Tononi (2000) calls “degeneracy”, see also Bailly and Longo (2006) (in this case, we have several structures fulfilling a same physiological function, that of breathing).

Finally, account taken of these remarks, since the characteristic times τ usually scale as $W_f^{\frac{1}{4}}$, where W_f is the mass of the intended organism, it is necessary to expect the correlation lengths to scale differently according to the mode of transport: respectively L_p in $W_f^{\frac{1}{4}}$ and L_d in $W_f^{\frac{1}{8}}$, following the definitions of L_p and L_d .

In the sequel, our characteristic times will more precisely refer to “relaxation times”, still in analogy to physics (see next footnote), yet in properly biological frame, in relation to retention and protention.

1.1 Critical states and correlation length

The physics of criticality and self-organized systems has massively entered the domain of biology since early ideas by Nicolis and Prigogine (1977), Bak et al (1988), Kauffman (1993) ... We further extended this approach, in direct reference to far from equilibrium systems in the sense of Prigogine, by considering living entities as being in an “extended critical situation”, beyond the pointwise analysis of critical transitions proper to physical theories, see Bailly and Longo (2008).

It is interesting now to consider that physical criticality is associated with a so-called critical slowdown (see for example Suzuki et al (1982): the relaxation time of a system tends to infinity when it goes near the critical point. The qualitative meaning of these situations in biology is that the effect of a stimuli would take a long time to stabilize (or, more generally, the organism would take a long time to “react” or “adjust”), if one views life as close or in an (extended) critical state. In particular, criticality would lead to very slow cognitive reactions. Even in a computationalist or behaviorist perspective (which is not ours), the elaboration/reaction time is necessarily slow in an organism with long correlations in space and slow characteristic time of the individual components of the system. However organisms and especially metazoans must often react quickly and are able to do so. Consequently, biological organization provides a solution to this paradox. This solution is to compensate this slowness by preparing the organism to a forthcoming stimulus *in advance*. We will try to provide a simple framework to tackle these properties, by an analysis of protention and biological inertia. Of course, in this context, perception itself is co-determined by this protentional activity.

2 Retention and protention.

2.1 Principles

We therefore consider *retention* R by specifying it under the form:

$R_k(t, t_0)$ at an instant t of an anterior “event” e of nature k at time t_0 ,

For short and if needed, we will pose that $e_0^k = e^k(t_0)$ (where $t_0 \leq t$).

Virtual protention, of an event of the same nature $e_1^k = e^k(t_1)$ at moment t of an ulterior instant t_1 ($t \leq t_1$) will be noted $V_{pk}(R_k, t, t_1)$. Hence, it will be considered as a function of retention R_k because, and this is an essential principle of our approach, in *the absence of the retention of an event of nature k there will be no possible protention for an event of such nature*. We will therefore have $V_{pk}(R_k, t, t_1) = 0$, for $R_k = 0$. For the sake of simplicity, we described this dependence of protention on retention as a linear dependence and our (actual) protention, $P = V_{pk}(R_k, t, t_1)$, will express this¹. Moreover, in conformity with our previous

¹ After reading a draft of this paper, L. Manning gave us references to IRM data confirming the neurophysiological and neuroimaging evidence for protention and the dependence of protention on retention: Szpunar et al (2007); Botzung et al (2008). Further, more specific experiments would be required in order to quantify the coefficients we introduce here and check/adjust the linearity of this dependence.

analyses, we will pose that this virtual protention is a monotonous increasing function of the retention in question, that is $\frac{\partial V_{pk}}{\partial R_k} \geq 0$.

2.2 Specifications

On the basis of the distinction made above, we have thus introduced the notions of retention and of virtual protention, as “immediate” and “passive” memory and anticipation in order to express the fact that what we have are phenomena that do not stem from the intentionality related to a conscious activity of a subject (generally endowed with a more or less elaborate nervous system), but to simple processes of biological reaction/stimuli/response, of which many primitive organisms in relationship to their environment are the locus. To the end of developing this point of view, we now introduce distinct concepts with effects which we propose to represent by means of simple functions, mainly *relaxation functions* and their combinations².

More specifically, we will first define the retention function:

$$R(t, t_0) = a_R \exp\left(\frac{t_0 - t}{\tau_R}\right) \quad (1)$$

t_0 is the time of occurrence of an event which is the object of the retention, t is the present moment ($t > t_0$); τ_R is the characteristic time associated to the decrease of the retention as we move away from the occurrence of the event and a_R is a coefficient which can be associated to an individual or to a species, for example, in comparison to others of which such faculties are more or less developed.

We propose to use relaxation functions, because the loss of retention, by moving away from the moment of the beginning of a phrase or, more generally, from the beginning of any action (including listening), can be considered as a sort of “return to equilibrium”. A necessary return if we want to grasp the meaning of the ensuing phrase or action. This, obviously, does not preclude us from maintaining a memory of a more long-term past (the initial part of a discourse, for instance): we limit ourselves to an analysis of the local, pre-conscious effect which contributes to the extended present of an ongoing activity.

How may we now formally define virtual protention, a property which belongs only to living phenomena? We propose to make it mathematically intelligible by means of a *temporal symmetry* with regard to R (time t will change sign). So we define, by a symmetry adjusted by two new parameters, a_P and τ_P , a *virtual* protention. Now, time t_1 is the time of the event to be anticipated and which is in the future of the present instant t ($t_1 > t$), in the form of the function:

$$V_P(t, t_1) = a_P \exp\left(\frac{t - t_1}{\tau_P}\right) \quad (2)$$

Where the different parameters, a_P and τ_P , play the same *mutatis mutandis* role as those which intervene in R (cf fig. A).

² Relaxation functions are among the simplest decreasing functions enabling to define a characteristic time τ in physics, they often represent the basic model for the return to the equilibrium of a system that was initially brought out of equilibrium, with the speed at which the system returns to the equilibrium f_e of the system's f function ($\frac{df}{dt}$) remaining proportional to this interval $\frac{df}{dt} = -\frac{|f-f_e|}{\tau}$.

Finally, we define *protention* $P(t, t_0, t_1)$ by the product RV_P :

$$P(t, t_0, t_1) = R(t, t_0)V_P(t, t_1) = a_P a_R \exp\left[\frac{t_0 - t}{\tau_R}\right] \exp\left[\frac{t - t_1}{\tau_P}\right] \quad (3)$$

The (linear) dependance of P on R , according to the principles stated above, emphasizes that such a capacity can only exist, phenomenologically speaking, if there exists in one form or another a sort of “memory” R (retention) relative to the event of which the reiteration or something resembling it is to be anticipated (we are aware that we are making a strong but empirically plausible hypothesis here, see footnote 1). In our view, the specific traits of this “expectation” of an unknown future, protention, is not exactly symmetrical with regard to the retention of a known past. And this by the fact that protention depends on retention – and not conversely – and that, by its nature, it remains “potential” (it is the expectation of a “possible” event).

In the case where $R = 0$ (complete absence of retention), the protention is cancelled out by the fact that there no longer exists any referent enabling to anticipate the expected event.

Still from the phenomenological standpoint, we will expect that in general $\tau_P \ll \tau_R$, that is, that the characteristic time of retention be greater than that associated to protention P (in order to “anticipate”, it is first necessary to “remember”, as stressed above). So the contribution of V_P in the definition of P (the second exponential in τ_P^{-1}), evolves more rapidly than that of retention for a same concerned duration. And we will always have $P \leq a_P R$, as a function of time t , and this for any values of τ_P and τ_R ($P = a_P R$ being achieved only in the very moment that the time to be anticipated is the actual present, that is for $t = t_1$ and hence $\exp\left[\frac{t - t_1}{\tau_P}\right] = 1$).

To make the role of the parameter t more explicit, with regard to the interval (t_0, t_1) and to the characteristic times τ_P , τ_R , some simple algebraic manipulations enable to put the expression P in the form of the product of a function of t and of a coefficient solely dependent on t_0 and t_1 , that is:

$$P(t) = a_R a_P \exp\left[\frac{\tau_R - \tau_P}{\tau_R \tau_P}(t - t_0)\right] \exp\left[\frac{t_0 - t_1}{\tau_R}\right] \exp\left[\frac{(\tau_R - \tau_P)}{\tau_R \tau_P}(t_0 - t_1)\right] \quad (4)$$

2.3 Comments

$\frac{\tau_R \tau_P}{(\tau_R - \tau_P)}$ is an interesting quantity: it has the dimension of a time and is the characteristic time of $P(t)$.

When τ_P tends to τ_R , this quantity tends to infinity, and then $\frac{(\tau_R - \tau_P)}{\tau_R \tau_P}$ to 0. When τ_P is close to τ_R , $P(t)$ is almost stationary as a function of t .

On the contrary, when $\tau_R \gg \tau_P$, minor changes in time strongly affect $P(t)$. More precisely, $P(t)$ is small when far from t_1 (and close to t_0), while it is very sensitive to (small) changes of t , when t is close to t_1 . This means that, in this condition, the vicinity of the virtual event is where the effect of protention is important, see figure 2.

It is crucial, however, to understand that protention, for example in the case of a cognitive situation, is not empirically associated with a change of behaviour, but with the *speed* of this change of behaviour. This suggests a way to approach these quantities empirically by a comparison of the reaction time between situations where the event associated with retention (at time t_0) actually occurs and when (at time t_1) it *doesn't*: a more sudden change is then to

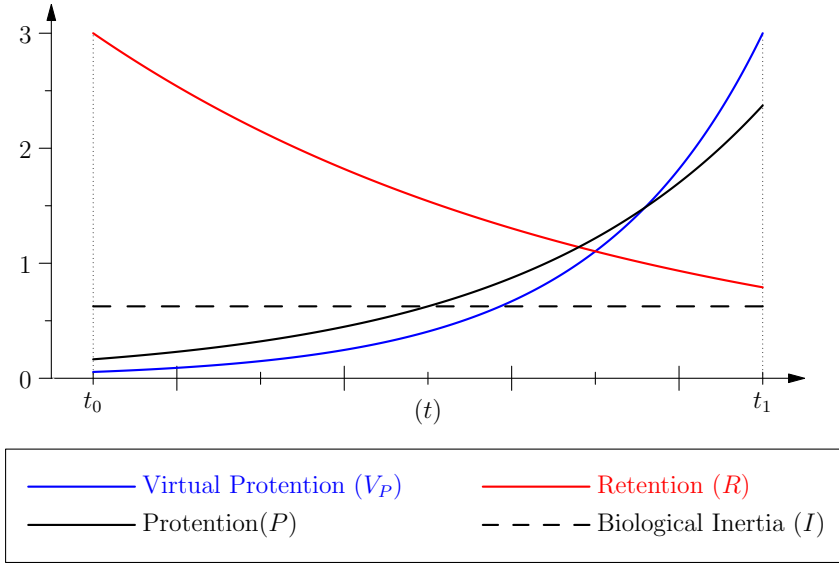


Fig. 1 Illustration of the basic quantities we define. Notice that protention is a growing function of time.

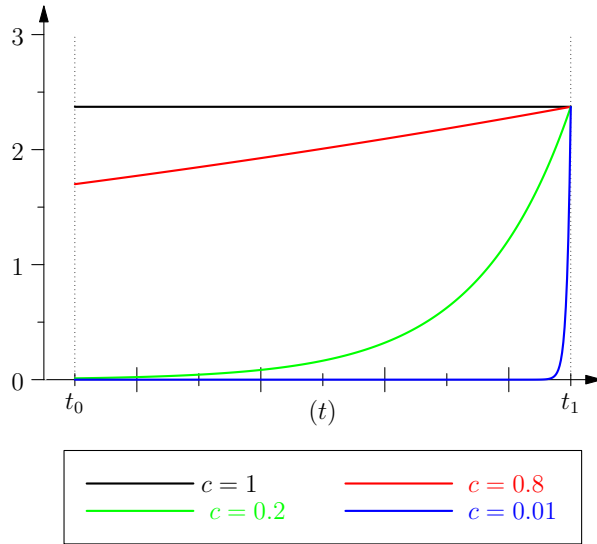


Fig. 2 Protention for various values of the ratio $c = \frac{\tau_P}{\tau_R}$. We observe that small value of c leads to a sharp curve near t_1 whereas value close to 1 are flat in the interval. We will discuss the biological meaning of this case in section 3.

be expected close to the the expectation time t_1 . In particular, the situation when the virtual event (at time t_1) doesn't occur should allow to evidenciate the presence of protention and to see a part of its effect, it is the case of amoeba in Saigusa et al (2008). It is quite clear that in many situations the effect of protentional action consists in a "sensibilization" to the virtual stimuli with the preparation of a response. This may lead to no behavioural change

when the virtual stimuli doesn't happen, but leads to a change of organization and possibly to a greater sensitivity to noise.

2.4 Global protention

One may wonder when protention is maximal for a given individual. In our approach, the first possible answer is given by looking at the diagram in figure 2: this quantity is maximal close to t_1 . However, we can refine the question (and the answer) by looking at the global amount of protention along the intended interval $[t_0, t_1]$. As protention is both variant and contravariant in the size of $[t_0, t_1]$ (see definition 3), this question has a non-obvious answer.

For this purpose, we define the notion of *global protention*, which is the sum (the integral) of protention over time, between t_0 and t_1 .

$$G_P(t_1 - t_0) = \int_{t_0}^{t_1} P(t) dt \quad (5)$$

$$= \frac{a_R a_P \tau_R \tau_P}{\tau_R - \tau_P} \exp \left[\frac{t_0 \tau_P - t_1 \tau_R}{\tau_R \tau_P} \right] \left(\exp \left[\frac{(\tau_R - \tau_P)}{\tau_R \tau_P} t_1 \right] - \exp \left[\frac{(\tau_R - \tau_P)}{\tau_R \tau_P} t_0 \right] \right) \quad (6)$$

$$= \frac{a_R a_P \tau_R \tau_P}{\tau_R - \tau_P} \left(\exp \left[\frac{t_0 - t_1}{\tau_R} \right] - \exp \left[\frac{t_0 - t_1}{\tau_P} \right] \right) \quad (7)$$

This quantity has a maximum for $t_1 - t_0 = \frac{\tau_P \tau_R}{\tau_R - \tau_P} \ln \left(\frac{\tau_R}{\tau_P} \right)$, this maximum is a compromise between the need to give the protention time to have effect (covariant dependence on the size of $[t_0, t_1]$) and the need to have points in $[t_0, t_1]$ that are close *both* to t_0 and t_1 (contravariance). This result means that there is a specific duration between the past event and the future event which optimize the protentional effects. This seems to be consistent with the results in Saigusa et al (2008). In section 3 we will go back to the relevant ratio $c = \frac{\tau_P}{\tau_R}$.

3 Biological inertia

The third exponential in eq. (4) does not depend on t . It may be then considered a coefficient of protention that we call *biological inertia* $I(t_0, t_1)$, between instants t_0 and t_1 .

In other words, protention may be considered as a function of time t (modulated by constants and characteristic times), of a retentive term ($\exp \left[\frac{t_0 - t_1}{\tau_R} \right]$) and of an “inertia”, a coefficient independent of t , but depending on the specific organism. This coefficient is to be understood as a capacity to “carry over by continuity” the present (structural) stability; or also, as an implicit bet by the living organism on the permanence of its own structure and on that of the “world”, correlated to retention. In section 4, by references and a discussion, we will say more about this new concept. First a few technicalities.

We have to check whether our definitions depend on the specific reference we choose. That is to say if a time origin change:

$$t_0 \leftarrow \tilde{t}_0 = t_0 + \Delta t \quad t_1 \leftarrow \tilde{t}_1 = t_1 + \Delta t \quad t \leftarrow \tilde{t} = t + \Delta t \quad (8)$$

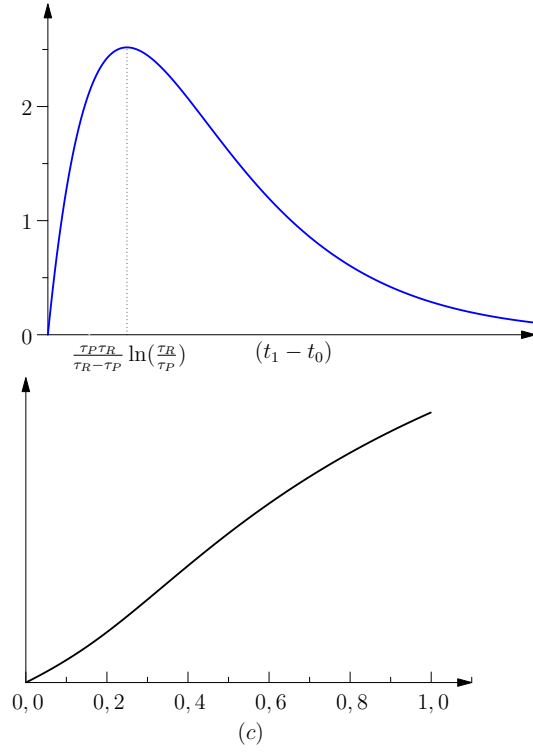


Fig. 3 *Global protention*. When considered as a function of the length of the time interval (LEFT), there is a maximum which corresponds to the greater effect of the couple Protention/Retention. RIGHT, we see the global protention as a function of $c = \frac{\tau_P}{\tau_R}$.

changes the way we split P in three parts, in equation 4. It is then straightforward to see that:

$$\exp \left[\frac{\tau_R - \tau_P}{\tau_R \tau_P} (t - t_0) \right] = \exp \left[\frac{\tau_R - \tau_P}{\tau_R \tau_P} (\tilde{t} - \tilde{t}_0) \right] \quad (9)$$

$$\exp \left[\frac{t_0 - t_1}{\tau_R} \right] = \exp \left[\frac{\tilde{t}_0 - \tilde{t}_1}{\tau_R} \right] \quad (10)$$

$$a_R a_P \exp \left[\frac{(\tau_R - \tau_P)}{\tau_R \tau_P} (t_0 - t_1) \right] = a_R a_P \exp \left[\frac{(\tau_R - \tau_P)}{\tau_R \tau_P} (\tilde{t}_0 - \tilde{t}_1) \right] \quad (11)$$

This means that each of these quantities has a proper biological meaning, in particular we can then define inertia as:

$$I(t_1 - t_0) = a_R a_P \exp \left[\frac{(\tau_R - \tau_P)}{\tau_R \tau_P} (t_0 - t_1) \right] \quad (12)$$

Inertia introduces a coefficient which is independent of t and is, in general, much smaller than 1 (and always smaller than 1). This coefficient contributes to the dependence of P in function of t . In particular, it contributes in an essential manner to the decrease of the protention according to the temporal distance.

3.1 Analysis

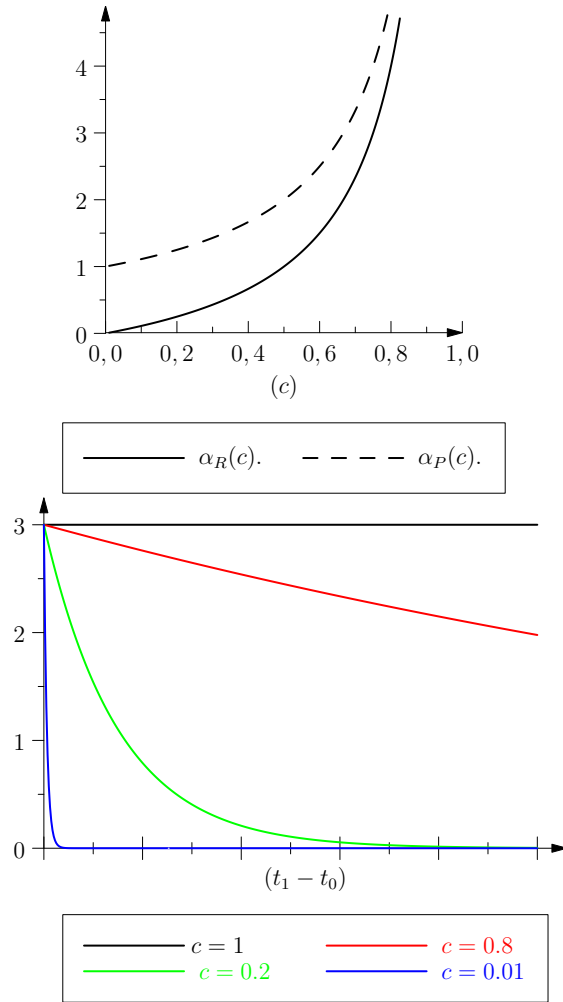


Fig. 4 *Biological inertia*. LEFT: we plot the factor of the characteristic time of biological inertia seen as protention (or retention). RIGHT: biological inertia as a function of the length of the time interval for various values of c .

In order to better understand the sense we attribute to this “inertia” of living phenomena, given our preceding remark regarding orders of magnitude respective of characteristic times, we may focus on the ratio c of figure 3, that is on c such that $\tau_P = c\tau_R$. We consider $0 \leq c \leq 1$ and rewrite I in the equivalent form:

$$I(t_1 - t_0) = a_R a_P \exp \left[\frac{(1-c)}{c \tau_R} (t_0 - t_1) \right] \quad (13)$$

$$= a_R a_P \exp \left[\frac{1}{\alpha_R(c) \tau_R} (t_0 - t_1) \right] \quad \text{with } \alpha_R(c) = \frac{c}{(1-c)} \quad (14)$$

Then I has the *form* of a “long term retention” if $c > 0.5$ or a “short term retention” if $c < 0.5$. Conversely, and maybe even more intuitively, inertia can be also interpreted (by writing $\tau_R = \frac{\tau_P}{c}$ and eliminating this time τ_R) as a “long term virtual protention” :

$$I(t_1 - t_0) = a_R a_P \exp \left[\frac{(1-c)}{\tau_P} (t_0 - t_1) \right] \quad (15)$$

$$= a_R a_P \exp \left[\frac{1}{\alpha_P(c) \tau_P} (t_0 - t_1) \right] \quad \text{with } \alpha_P(c) = \frac{1}{(1-c)} \quad (16)$$

Biological inertia would then be both an extended retention, eq. (13), and a virtual protention, eq. (15), which are both *independent* of the time t of the action: in fact, it depends only on the instants that are relevant to the event retained and occurring in t_0 or which is the object of an expectation (protention towards t_1). It is therefore an inertia which “carries over” the life form from t_0 towards t_1 , by the preservation of its own structure and its relationship with the environment (see section 4).

The $\tau_R = \tau_P$ case

It can be observed that in the case where the characteristic retention and virtual protention times are equal ($\tau_R = \tau_P = \tau$ where the c from the equation above is equal to 1), the protention P becomes $a_R a_P \exp \left[\frac{(t_0 - t_1)}{\tau} \right]$ and is therefore independent of the present observation time t . This, of course, within the interval between the moment of the occurrence of the event in question and the moment t_1 where it is mobilized again (since we still have $t_0 < t < t_1$). But then, according still to hypothesis $c = 1$, one has $P = a_R a_P \exp \left[\frac{(t_0 - t_1)}{\tau} \right] = I(t_0, t_1)$. In this case, P takes its minimal value, if we consider it as a function of the non-negative value $(\tau_R - \tau_P) \geq 0$. Thus, when $(\tau_R = \tau_P)$, only inertia is present in protention.

We can also note this situation by considering that if the observation time t is close to the instant t_0 of the occurrence of the event (recent retention), then the temporal interval for a virtual protention, $(t - t_1) \approx (t_0 - t_1)$, increases; conversely, if time t is far from t_0 (remote retention), the temporal interval involved in this virtual protention and within which the latter plays its role (the future of the observation moment t) diminishes in importance, given of course that the protention P as such remains independent of t , in this case.

These remarks are meant to highlight the fact that, in the latter case, the *intensity* P of the protention remains invariant, whereas the duration upon which virtual protention takes place — the future of t — can change in size: $t_1 - t$.

4 References and more justifications for biological inertia

We have come to propose a mathematical notion of biological inertia through an apparently arbitrary play of symmetries and calculations, of which we would now like to better

explain the meaning and the objectives. To emphasize the importance of the concept, but without wanting to make excessive and uncontrolled analogies with immensely illustrious precedents, let's note that modern physics started off with a good analysis of inertia, as a "pursuing a state" without aim nor teleology: Galilean inertia³.

In biology, this notion can already be found, although rarely, under various forms. For Vaz and Varela (1978) "the lymphoid system has an *inertia*, which resists attempts to induce sudden and profound deviations in the course of events". So this is a weak notion of inertia, close to the "persistence" of structural stability. Likewise, we could talk about inertia in the case of the notion of "dynamic core" presented in Edelman and Tononi (2000), because it also refers to the continuity/persistence of individuation (see also Le Van Quyen (2003)). This theme is also used by Varela (1997), where the term of inertia appears also in the attempt to grasp the "force", specific to any organism, enabling its "bringing forth of an identity".

In our approach, which is inspired by the methods of physics without identifying with it, we firstly define retention by a relaxation function, which is a physical notion — which can even be considered as adequate to describe the "memory" to which some often refer in relation to certain physico-chemical activities. Virtual protention is given then by a temporal symmetry, *modulo* some adjustment coefficients; this notion, which has no analogy in physics, is by this, and at least, the "projective" reflection of retention. Protention follows, as a linear combination of these two values, in function of time. Then, by a simple algebraic device, we separate the part containing the temporal variable from the functional definition: what remains is a constant, a function of all other parameters (characteristic times, specific constants, interval range), which we called biological inertia. As we pointed out, when retention and protention have the same characteristic times ($\tau_R = \tau_P$), inertia coincides with protention. We would then say that this is the simplest situations from a cognitive viewpoint: the organism can only anticipate by means of inertia. In any case, the proposed notion of inertia appears to clearly specify the informal idea of "bringing forth of an identity", with the reference to retention and to protention, at the minimal cognitive level.

But why would this inertia not simply correspond to the fact of following a geodesic trajectory, like in physics? Some will say that the amoeba, the paramecium, etc., follow a gradient in the same way that a physical object follows the trajectory dictated by the Hamiltonian (through the principle of least action). It may appear that such is the case in *in vitro* experiments where, within a highly purified environment, the unicellular organism is exposed to one or two very specific gradients (chemical, thermal...). On the other hand, in an *in vivo* situation, in the ecosystems preferred by such animalcules (and which are very polluted, from our standpoint) they must "arbitrate" between qualitatively different stimuli: several physico-chemical gradients, an edible and close bacterium that is not too large, another smaller one, etc. Now the paramecium, say, appears to "learn" (see [Mislin, 2004]), that is, it enjoys at least retention, which contributes to protention (and, after reading Mislin and references, one could posit for it $\tau_R > \tau_P$, or even $\tau_R \gg \tau_P$)⁴. And it is difficult to conceive of learning without error, or without several attempts and without the memory of these attempts (retention), even if such memory is extremely rudimentary. The subsequent

³ Without forgetting Giordano Bruno who had an informal yet quite relevant notion of inertia, a few years prior to Galileo. It then became possible to understand planetary movements without God being required to push the planets around at all times. We similarly aim at a concept of inertia for living phenomena with no reference to "vital impetus" or divine thrust.

⁴ A paramecium manages the movements of about 2,000 cilia during highly complex swimming activities; some of its cilia also serve to direct food towards a "mouth" (opening upon the membrane), by means of very articulate movements.

action is therefore one among many possible ones, from the standpoint of the ecosystem, because it also depends on the specificity of individual retention (experience). Among these many possible trajectories, the one it follows has only to be *compatible* with the ecosystem. No gradient or physical geodesic is adequate to describe this plurality of possibilities of evolution, phylogenesis, ontogenesis and of action, which also depends on the specificity, hence on the history, of the species or of the individual (retention and biological inertia). Our modest inertial attempt tries to do this, in a way that is as preliminary as mathematically simple.

But why do we express a greater cognitive “complexity” with the growth of $(\tau_R - \tau_P) \geq 0$? It appears that the protention, when $\tau_R \gg \tau_P$, must account for more “experience” in order to achieve the objective of the action; it depends upon a greater amount of lived and retained history, and hence on a greater specificity (individuality) of the living object. So it better participates to the incessant process of individuation, which is a play between the richness of retention and the diversity of possible future trajectories.

5 Towards human cognition. From trajectory to space: The continuity of the cognitive phenomena

The continuity of space-time, which the mathematics of continua proposes and structures in a remarkable way, from Euclid to Cantor, follows — and does not precede — the continuity of a figure, of a contour or of a trajectory. Euclidean geometry is not a geometry of space, it is a geometry of figures, with continuous edges, constructed by means of a rule and a compass and submitted to deformations, to translations and to rotations. In short, it is a geometry of the gesture and of trajectories. It is much later, with Descartes (and a few predecessors: ideas always have a history), that geometry finds its constitutive environment in an abstract space, underlying and independent from the figures which evolve within. The analytical reconstruction of Euclidean geometry will follow, precisely by means of this ideal framework, an algebraico-geometrical continuum, organized in Cartesian coordinates. Then, since Cantor, we have a fantastic reconstruction of the underlying continuum, a possible one, though (see Lawvere and Bell for an alternative topos-theoretic approach, with no points, J. (1998)).

Let’s now try to grasp a possible constitutive trajectory or even a cognitive foundation of this *phenomenal* continuum which is the privileged conceptual and mathematical tool for the intelligibility of space, on the basis of our analysis of retention and of protention.

The recent analyses of the primary cortex (see Petitot (2008) for a survey) highlight the role of intracortical synaptic linkages in the perceptual construction of edges and of trajectories. Neurons which correlate themselves, approximately and locally, upon a straight or parallel line are more strongly connected than others. These neurons are sensitive to “directions”: they activate when detecting a direction, along a tangent. Thus, the continuity of an edge or of a trajectory is constructed by “gluing” together these tangents, in the precise geometrical (differential) sense of gluing. In other words, we force by continuity the unity of an edge by relating neurons which are strongly linked together and are, locally, almost in parallel, since the neurons which activate for *almost* parallel directions are more connected than the others. By this, the activation of a neuron stimulates or prepares for activation of neurons that are almost aligned with it or that are almost parallel, in the primary cortex.

This phenomenon participates in the retention and the protention of a *non-existing* line, a trajectory say, by “integrating”, in the mathematical sense, the tangents that are locally almost straight. The related inertial phenomena of the activation/deactivation of neurons may

be one of its constitutive elements, with inertia as a coefficient of protention. The retention of ocular movements or saccades which follow a moving body, an edge, should also be quoted: this retentive/protensive phenomenon originates in the muscles enabling the saccades or in the neurons managing them. As for the case of protention, in particular, there are protentional displacements in the receptor field of the cortical neurons that *precede* the saccades (Berthoz (2002)). The brain prepares itself and anticipates a moving object, of which the movement is perceived following an ocular saccade, or of which the trajectory or edge is perceived by running the eye along or over it. This is, in our view, the keystone of a fundamental protentional activity.

Now, we propose the following conjecture. First, the World is not continuous, nor discrete: it is what it is. Since Newton and Cantor, by continuous tools, or, now, in Quantum theories and Topos Theoretic approaches, we mathematically organized it in different ways. In our view, the phenomenal continuity of trajectories, of an edge, is due to the *retention* of that trajectory, edge, scanned by the eye, which is “glued” with the *protention* by the very unit of the cerebral and global physiological activity (the vestibular system, for example, has its own retention and inertia). It would then be this “gluing” — a mathematically solid concept (at the center of differential geometry, of which Riemannian geometry is a special case) — that entails the cognitive effect which *imposes* continuity upon the world: the image of the object and of its past position is reassembled (glued by the conjunction of protention and retention) with that of the object and of its expected position. We could indeed imagine that an animal with no fovea (the part of the eye which enables a follow up of a target by a continuous focus), a frog for example, and which takes spaced out snapshots of an object in movement would not have the impression of a continuous movement in the way in which we, the primates, “see” it.

So the continuity of a trajectory or of an edge is, in our opinion, the result of a spatio-temporal reassembling of the retentions and protentions that are managed by global neural activity in the presence of a plurality of activities of such type (muscles, vestibular system... but also the differentiable continuity of the movement or gesture participates by means of its own play of retention/protention). In short, by a cognitive process of glueing, we attribute continuity to phenomena which are what they are (and which a frog surely sees quite differently). Then, by a remarkable conceptual and mathematical effort having required centuries, we have even come to theorize, as abstract lines, surfaces and their edges, first, and then even the continuity of environing space, as the background of these structures. And this is the consequence, we believe, not the cause of the cognitive/perceptive continuity of the movement and of the gesture, which is instead grounded on the unity of protention and retention (note that, in this perspective, the continuity of an edge would also be the continuity of a movement: the movement of the saccade or of the hand caressing it, both retained and protended).

Let’s note that, in our attempt towards spatialization of time for living phenomena, in this paper and in Bailly et al (2010), — a spatialization which, although schematic, should contribute to its intelligibility — we have proceeded, in this section, along the opposite approach: a sort of temporalization of space. Its apparent continuity would be the result of a cognitive activity *on* time, the extended present obtained by retention and protention.

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